

A Reactive Strategy for High-Level Consistency During Search

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Acknowledgements

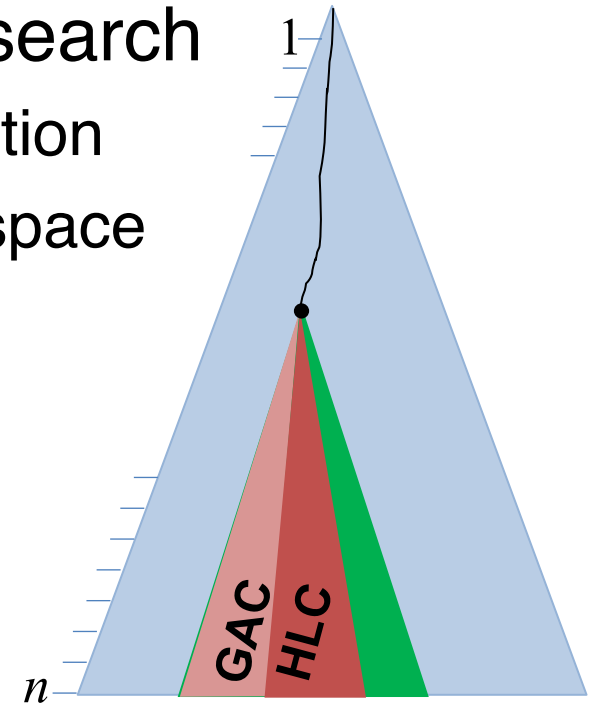
- Experiments conducted at UNL's Holland Computing Center
 - NSF Grant RI-111795, RI-1619344
 - NSF GRF and Chateaubriand Fellowship
 - ANR Demograph (ANR-16-CE40-0028) and Contredo (ANR-16-CE33-024)
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Context

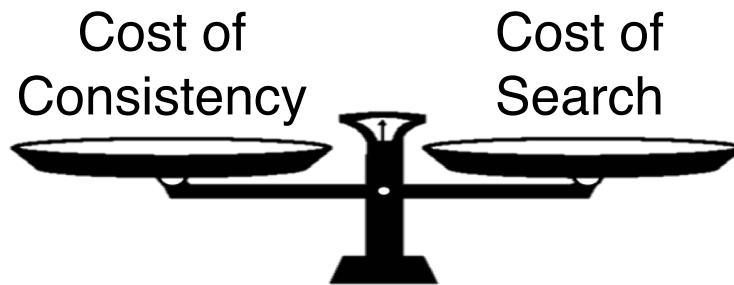
- Solving a Constraint Satisfaction Problem (CSP)
 - Conditioning: Backtrack search
 - Inference: Enforcing consistency
 - Consistency **properties** (e.g., GAC)
 - Constraint propagation **algorithms**
- Consistency during search
 - Constraint Programming solvers: GAC or weaker
 - CSP research: GAC or stronger
- Our focus: Higher-level consistency (HLC)

Lesson and Problem

- Maintaining consistency during search
 - Enforced at each variable instantiation
 - Prunes subtrees, reduces search space
- Stronger consistency
 - Filters more subtrees
 - But is costlier to enforce

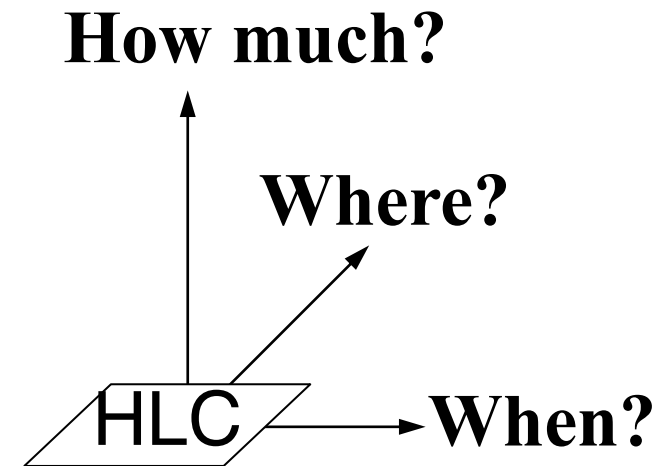
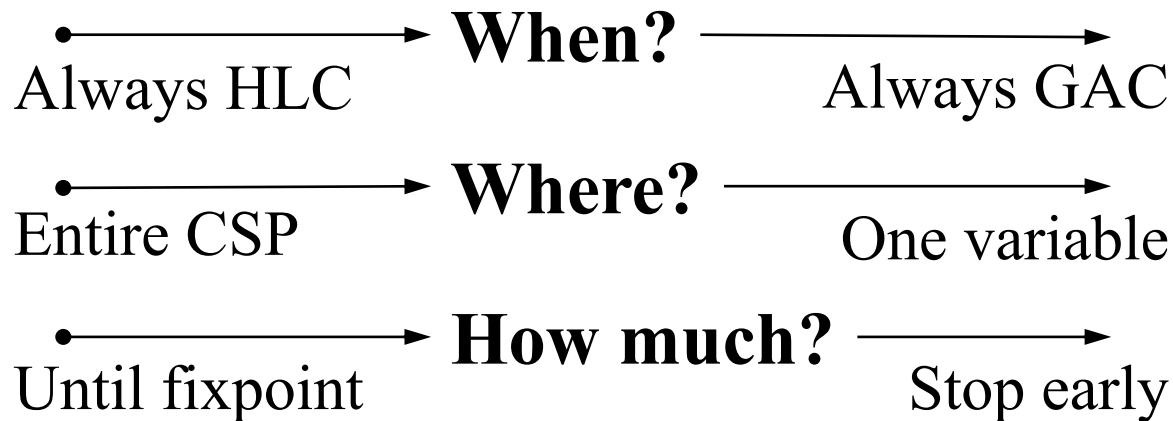


GAC vs HLC



Challenge

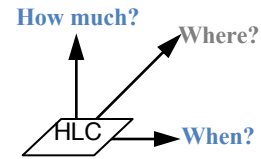
Decide **when, where, and how much** HLC to enforce during search



Our solution

1. When: PREPEAK

- Monitors search performance
- When search starts thrashing, triggers an HLC
- Then, conservatively reverts to GAC

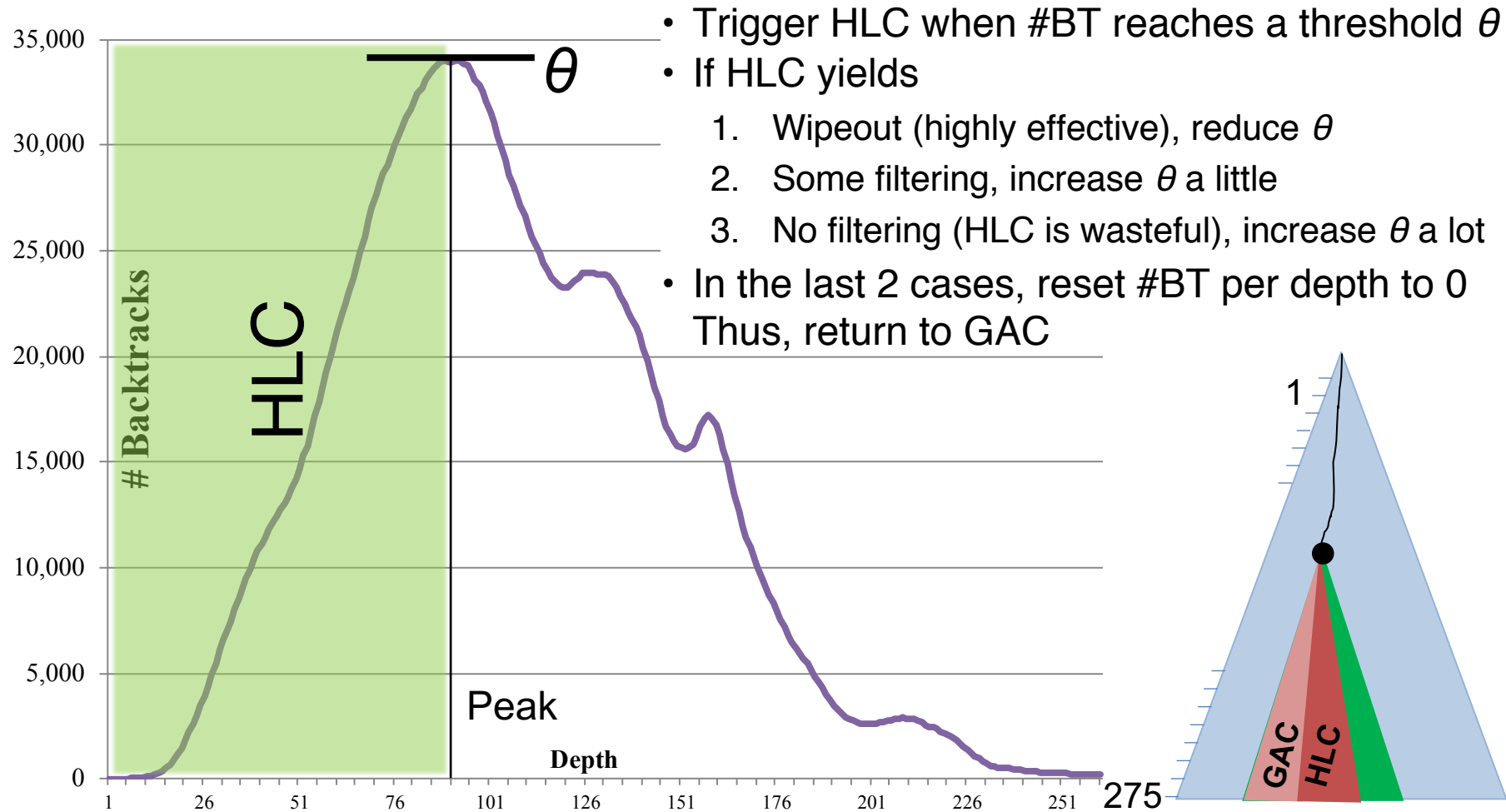


2. How much

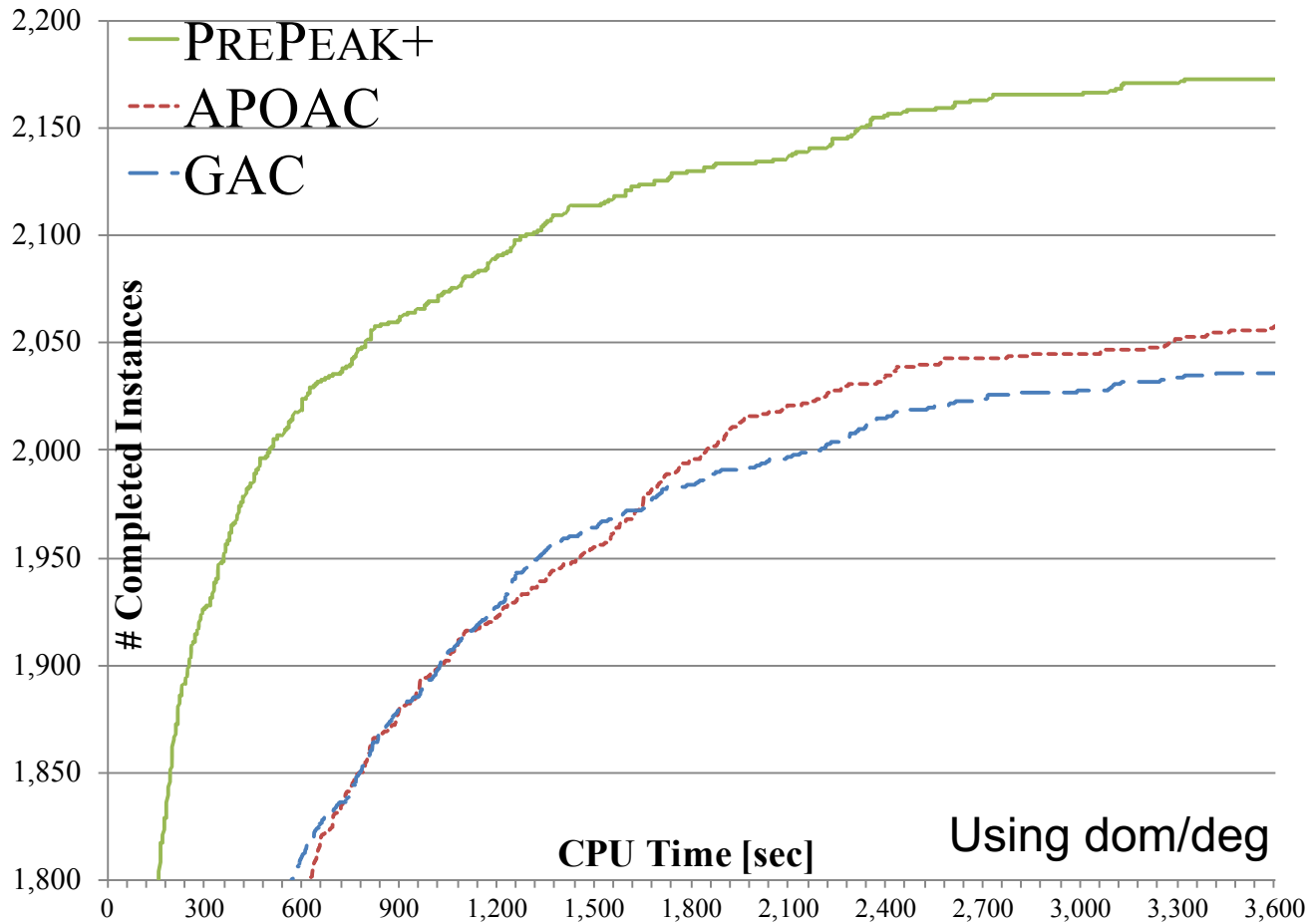
- Monitor propagation and interrupt before fixpoint

PREPEAK⁺ = PREPEAK + 'How Much'

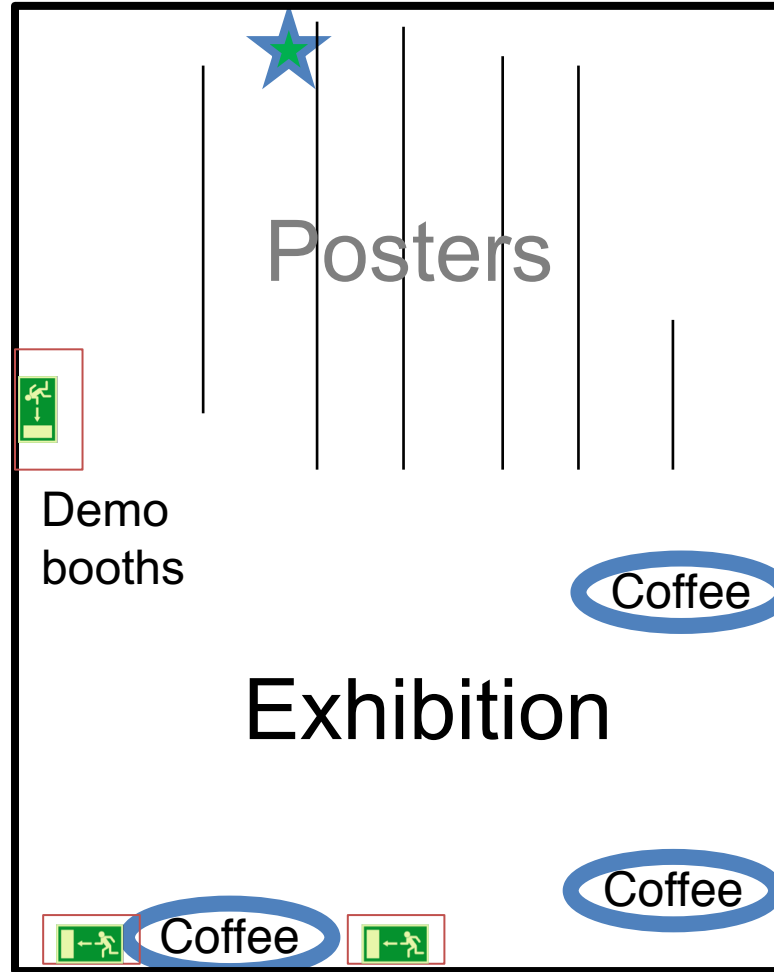
PREPEAK examines #BT per depth



Empirical Evaluations



Thank You



Goal state

Possible
start states

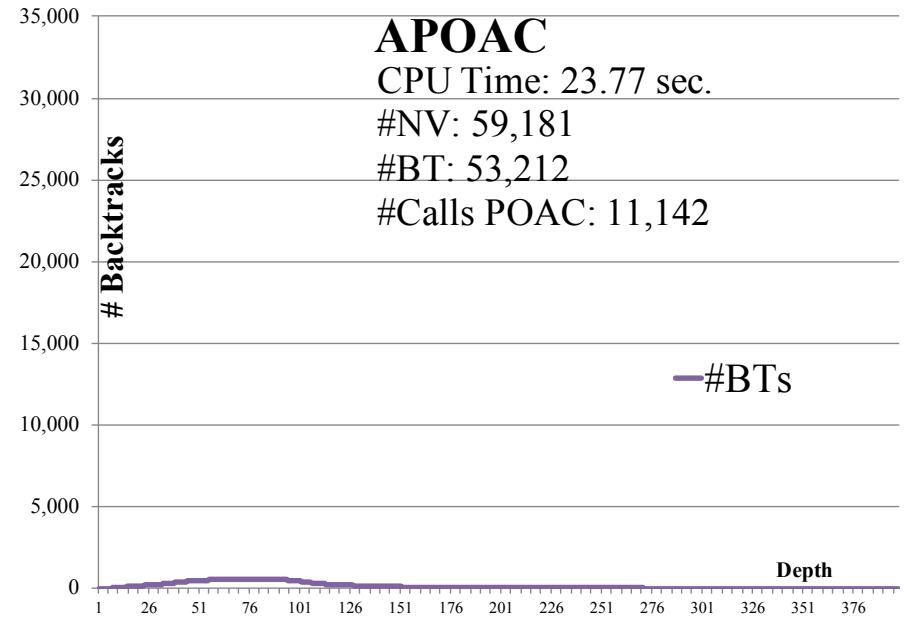
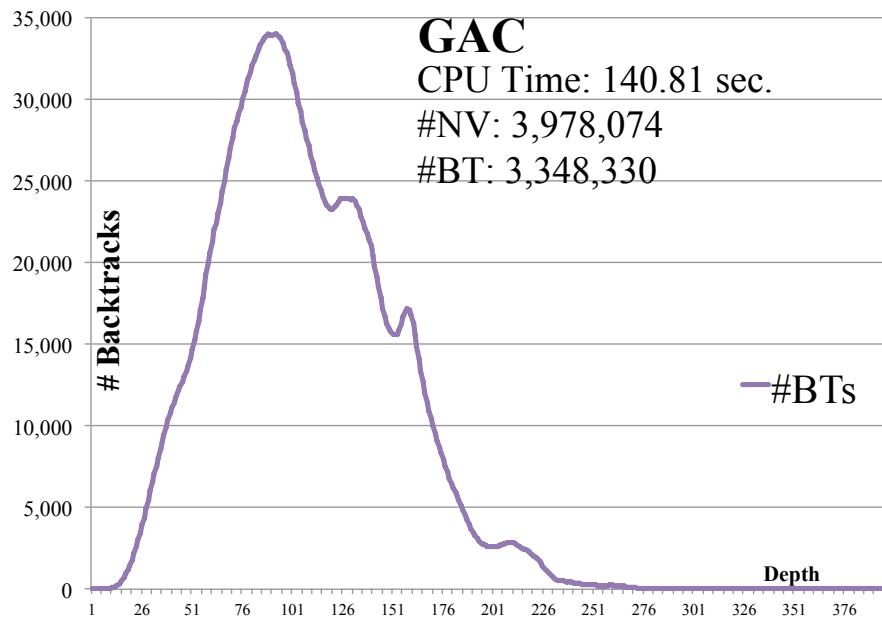
Thank You

Questions & Comments



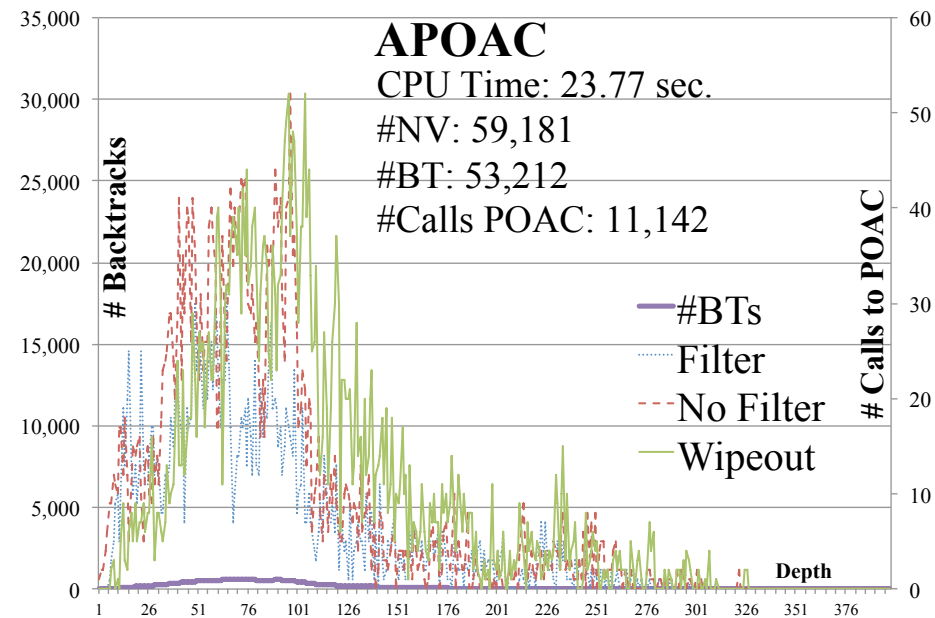
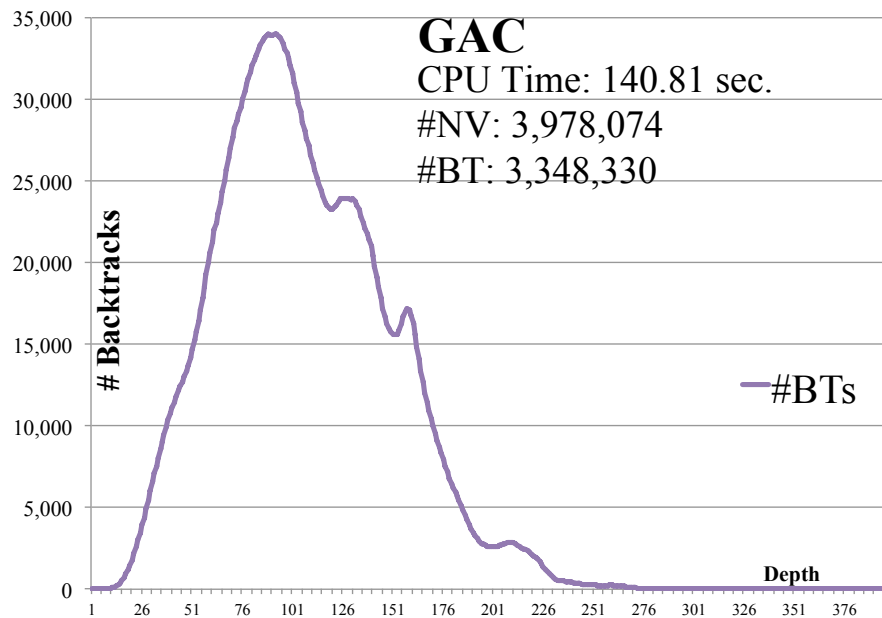
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Visualization of Benefit



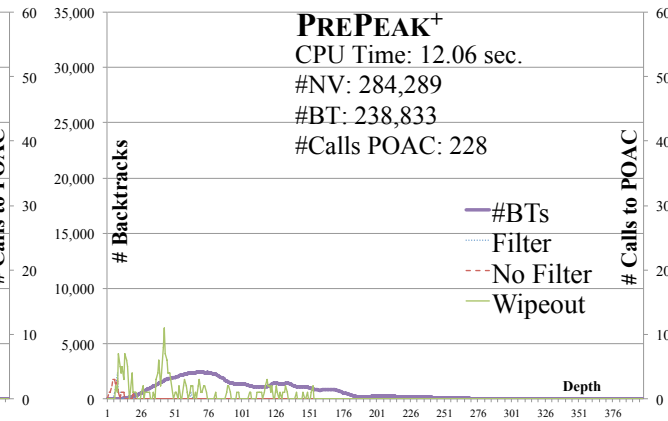
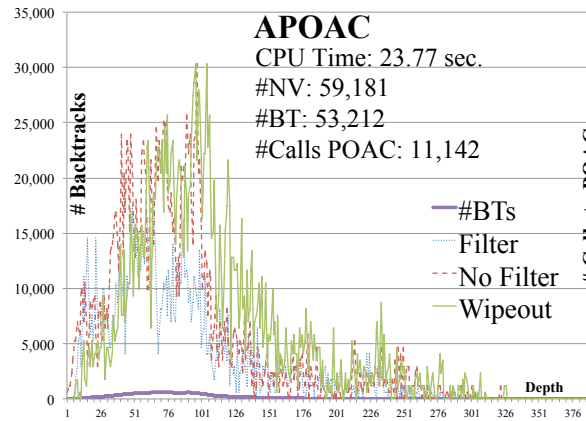
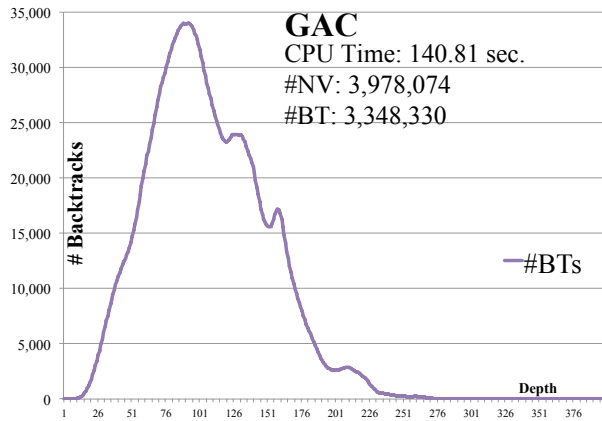
pseudo-aim-200-1-6-4, dom/wdeg

Visualization of Benefit



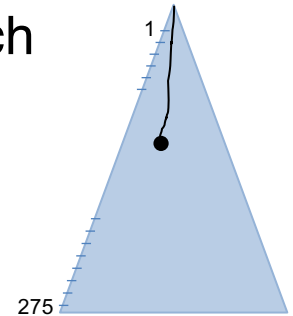
pseudo-aim-200-1-6-4, dom/wdeg

Visualization of Benefit



PREPEAK A Reactive Strategy for HLC

- Keep track of $btcount[\cdot]$, number of backtrack during search
- When $btcount[\cdot]$ reaches a given threshold θ
 - Enforce GAC then HLC as long as HLC yields domain wipeout for all values in domain of current variable
 - If backtrack, **reduce threshold** and keep enforcing HLC
 - If HLC finds a consistent value, reset $btcount[\cdot]$, **increase threshold a little**
 - If GAC finds a consistent value, reset $btcount[\cdot]$, **increase threshold a lot**



- Geometric laws to update threshold

- **Wipeout:** $\theta_{k+1}^{bt} \leftarrow r_w \cdot \theta_k^{bt}, r_w = 1.2^{-1}$
- **Filtering:** $\theta_{k+1}^{bt} \leftarrow r_f \cdot \theta_k^{bt}, r_f = 1.2^2$
- **No filtering:** $\theta_{k+1}^{bt} \leftarrow r_n \cdot \theta_k^{bt}, r_n = 1.2^3$

